



Carnegie Mellon University
Language Technologies Institute

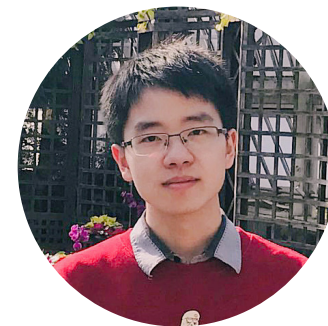
Neuro-Symbolic Language Modeling with Retrieval Automaton

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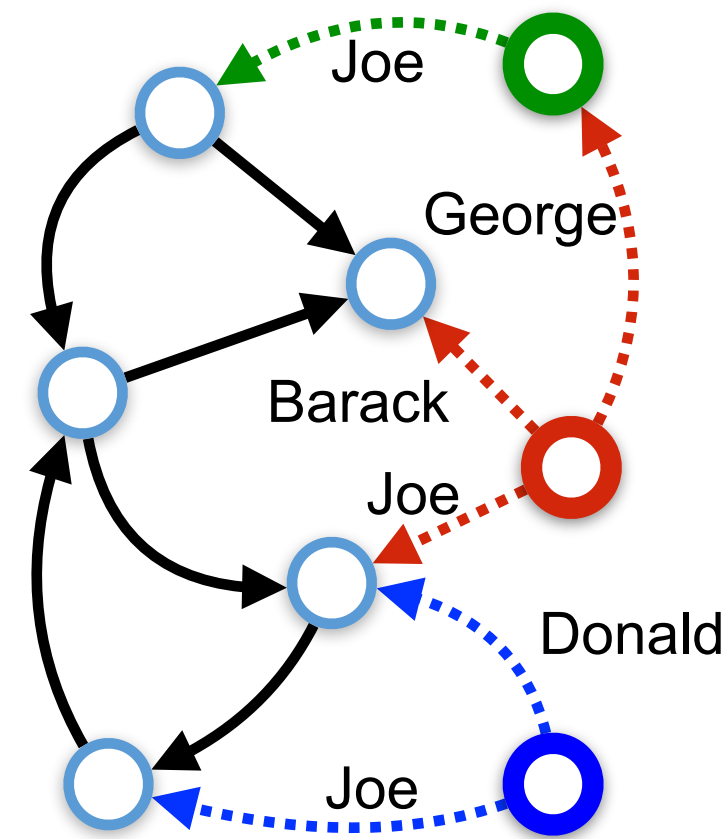
RetoMaton - TL;DR:

Given a trained LM and its training corpus, we construct a **weighted finite-state automaton**.

At **inference** time, we traverse the automaton in parallel with the LM.

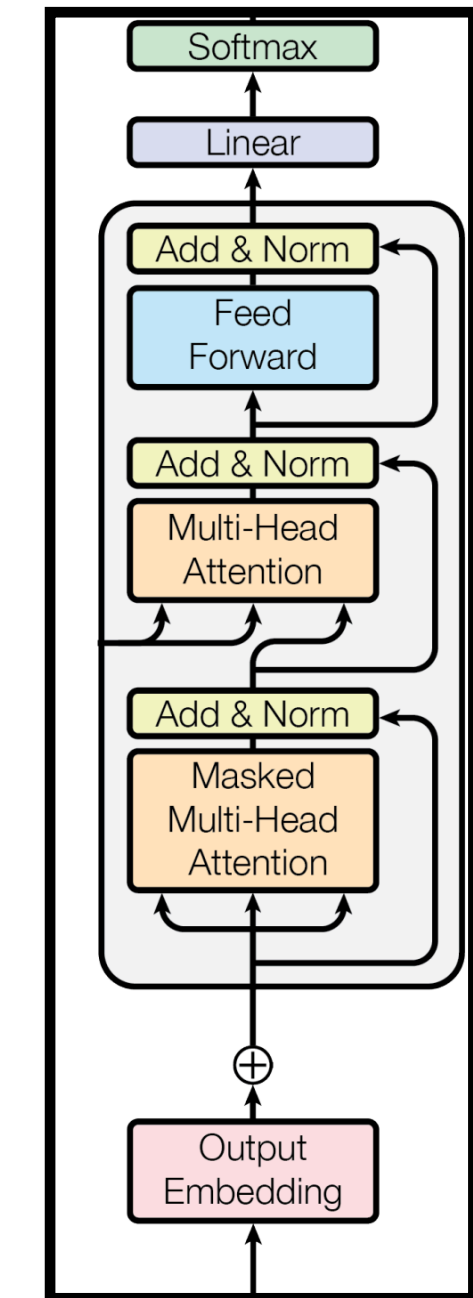
We **interpolate** this automaton's probability with the base LM's probability.

Automaton



- States: clusters of training examples, encoded by the LM
- Edges: pointers between consecutive examples, shared in cluster
- Weights: $-\|h^{(t)}, h_i\|_2$

Trained LM



$$\lambda P_{auto} + (1 - \lambda) P_{LM}$$

Background: K-Nearest Neighbor Language Model (k NN-LM) (Khandelwal et al., ICLR'2020)

Training

k NN search



Test

The	president	is	—
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Background: K-Nearest Neighbor Language Model (k NN-LM)

(Khandelwal et al., ICLR'2020)

Training

Context Next word



... by the president Joe Biden ...

k NN search



Test

The president is _____

Background: K-Nearest Neighbor Language Model (k NN-LM)

(Khandelwal et al., ICLR'2020)

Training

Context Next word

... by the president Joe Biden ...

k NN search

Test

time t

The president is Joe

Joe

Background: K-Nearest Neighbor Language Model (k NN-LM)

(Khandelwal et al., ICLR'2020)

Training

Context Next word

... by the president Joe Biden ...

k NN search



Test

time t

The	president	is	Joe
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Training

Context Next word

... by the president Joe Biden ...

k NN search

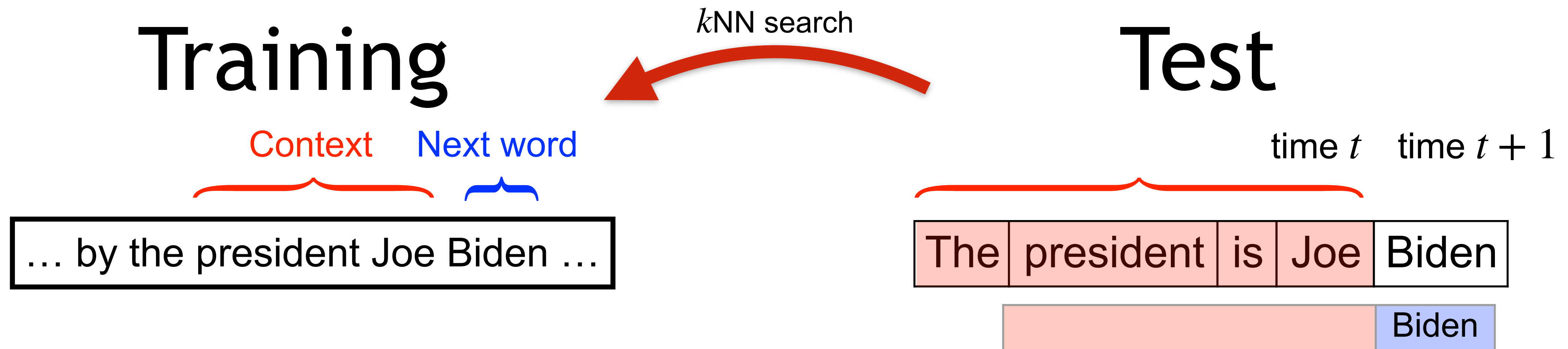
Test

time t time $t + 1$

The president is Joe Biden
Biden

Background: K-Nearest Neighbor Language Model (k NN-LM)

(Khandelwal et al., ICLR'2020)



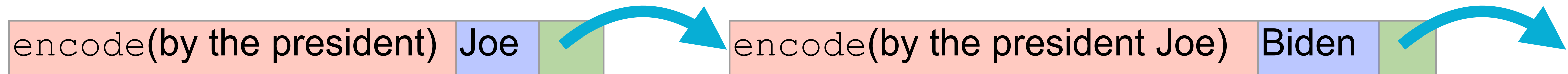
K-nearest neighbor search: for **every generated token**
time (k NN search) \gg time (forward pass)

If we performed **k NN search** to retrieve “Joe”,
can we save the search when predicting “Biden”?

Adding Pointers Between Datastore Entries

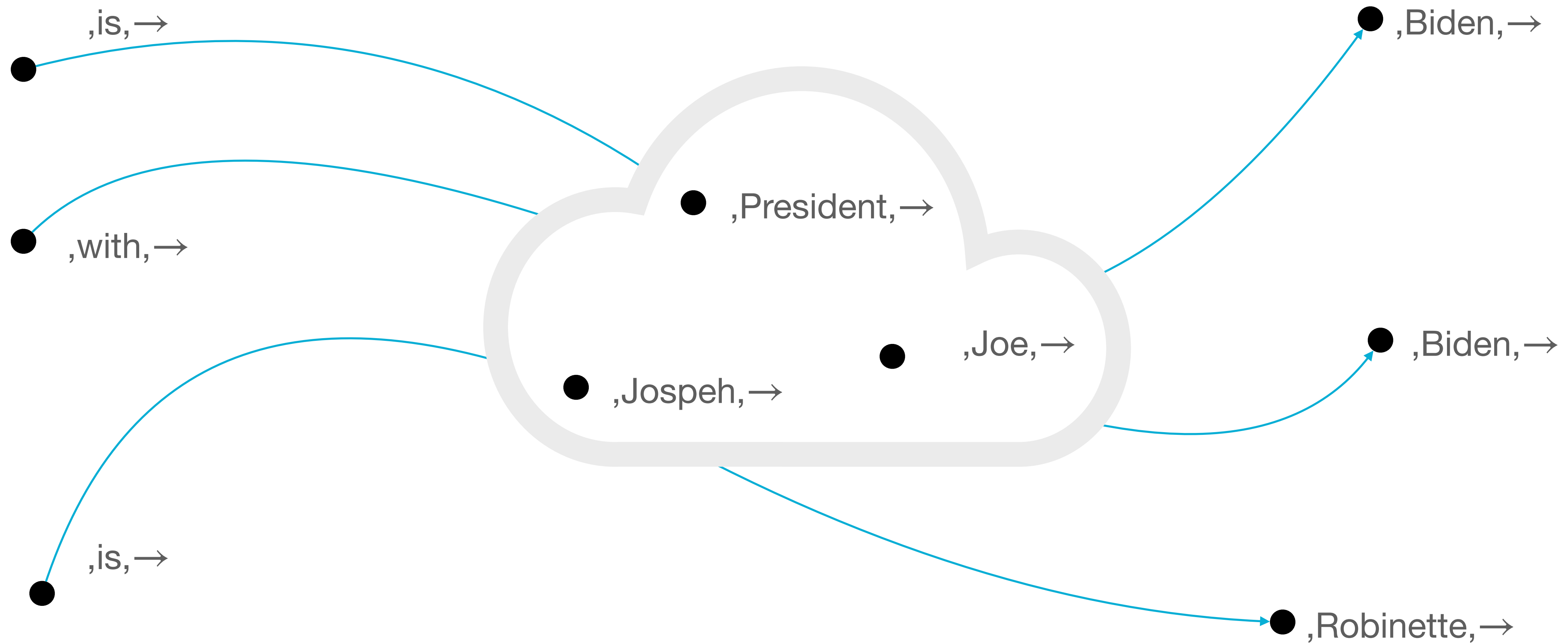
Training

... by the president Joe Biden ...

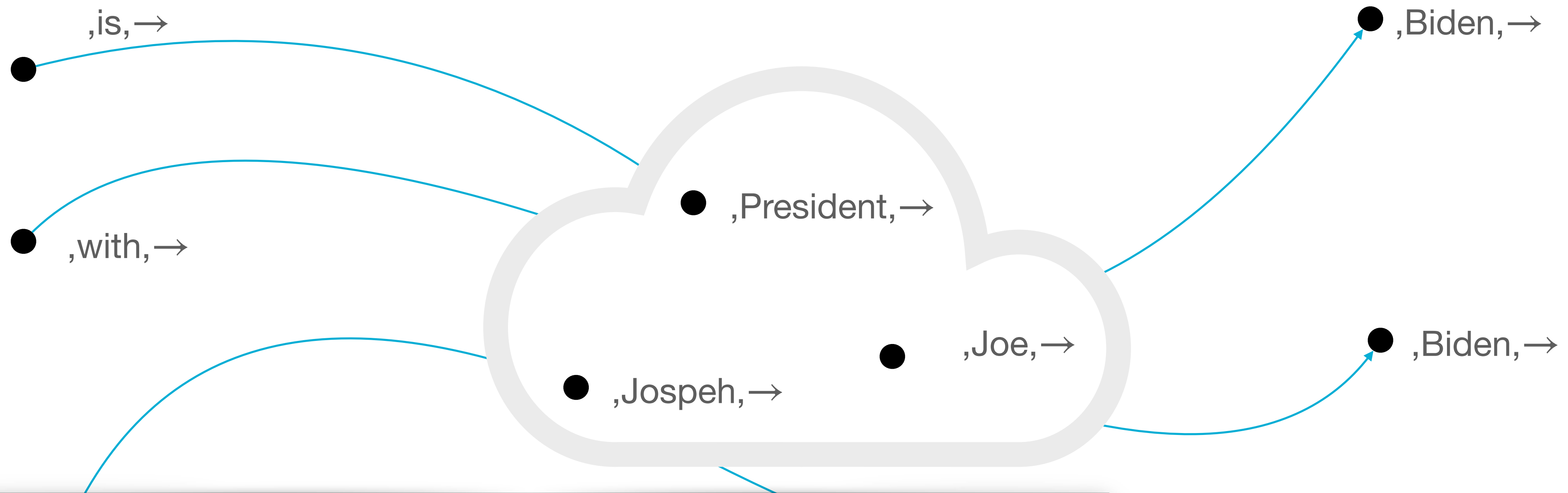


We still need to perform **k NN search** once, but in the following time steps, we can just follow pointers instead!

Clustering Entries with Close Keys



Clustering Entries with Close Keys



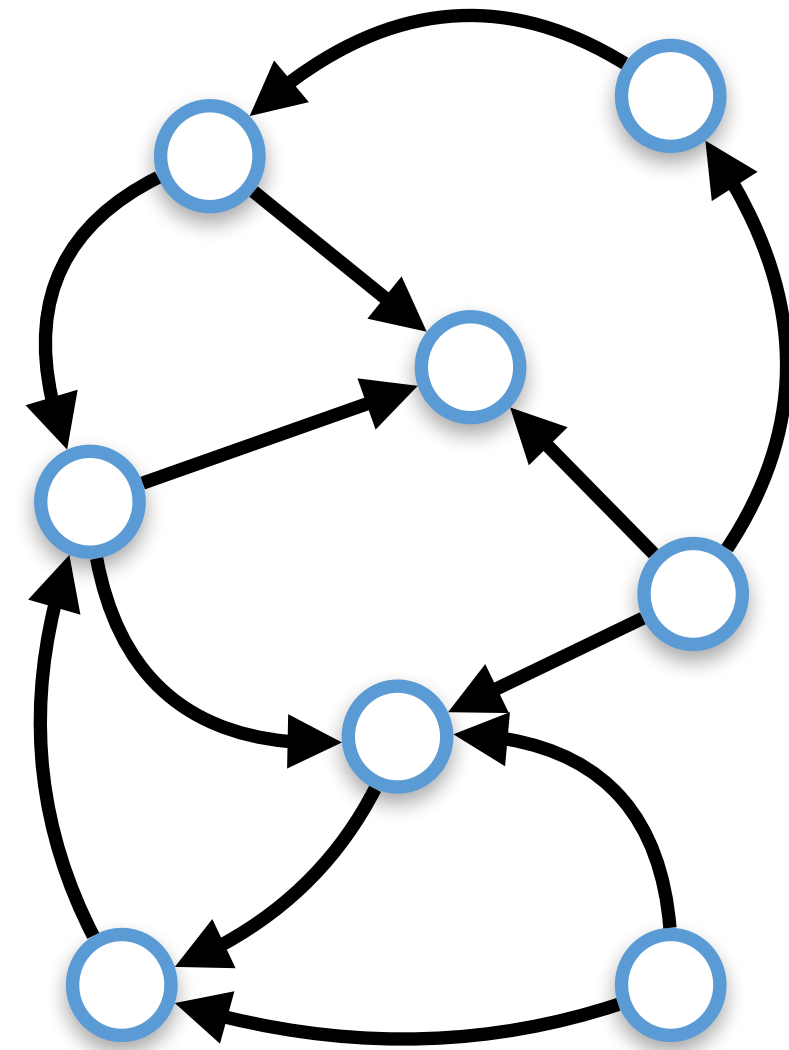
Cluster such entries, and share their outgoing pointers

👍 Capture n-grams that were unseen at training time

👍 Longer pointer traversal, without backing up to k NN search

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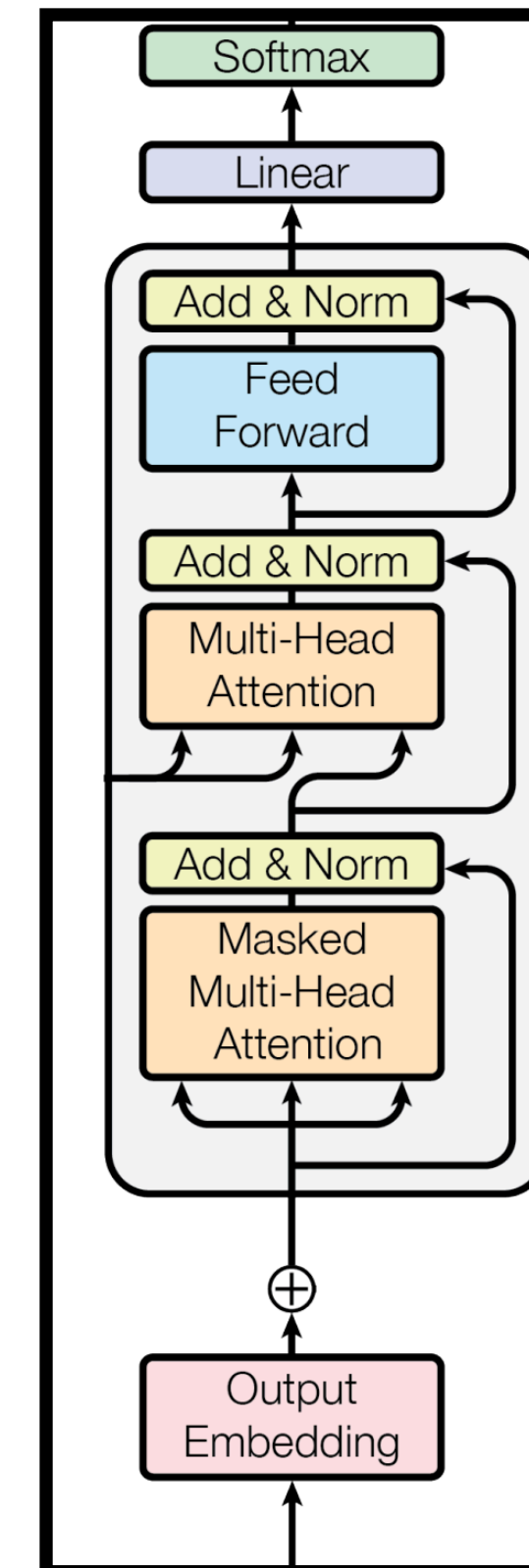
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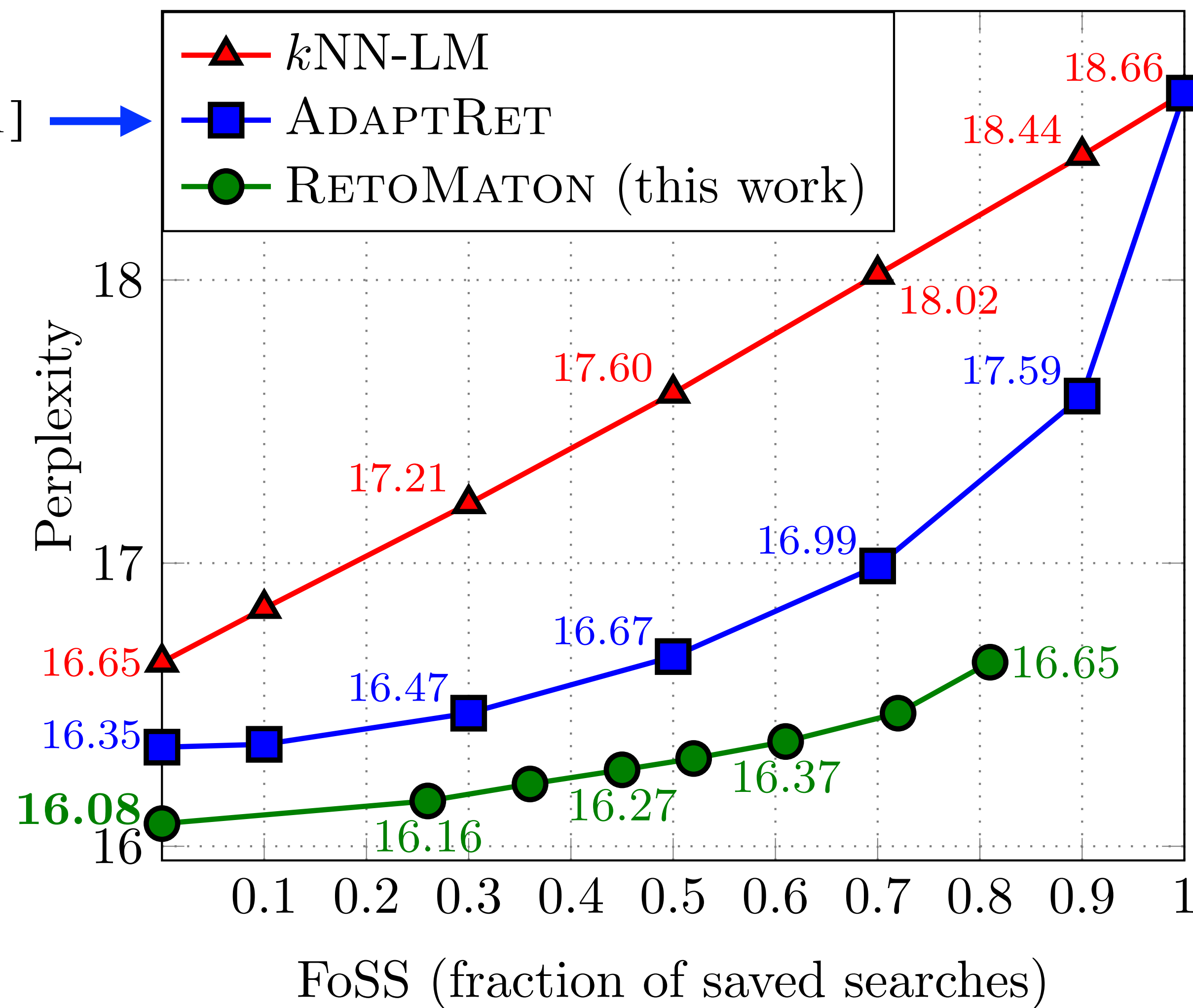
$$\lambda P_{auto} + (1 - \lambda) P_{LM}$$

Trained LM



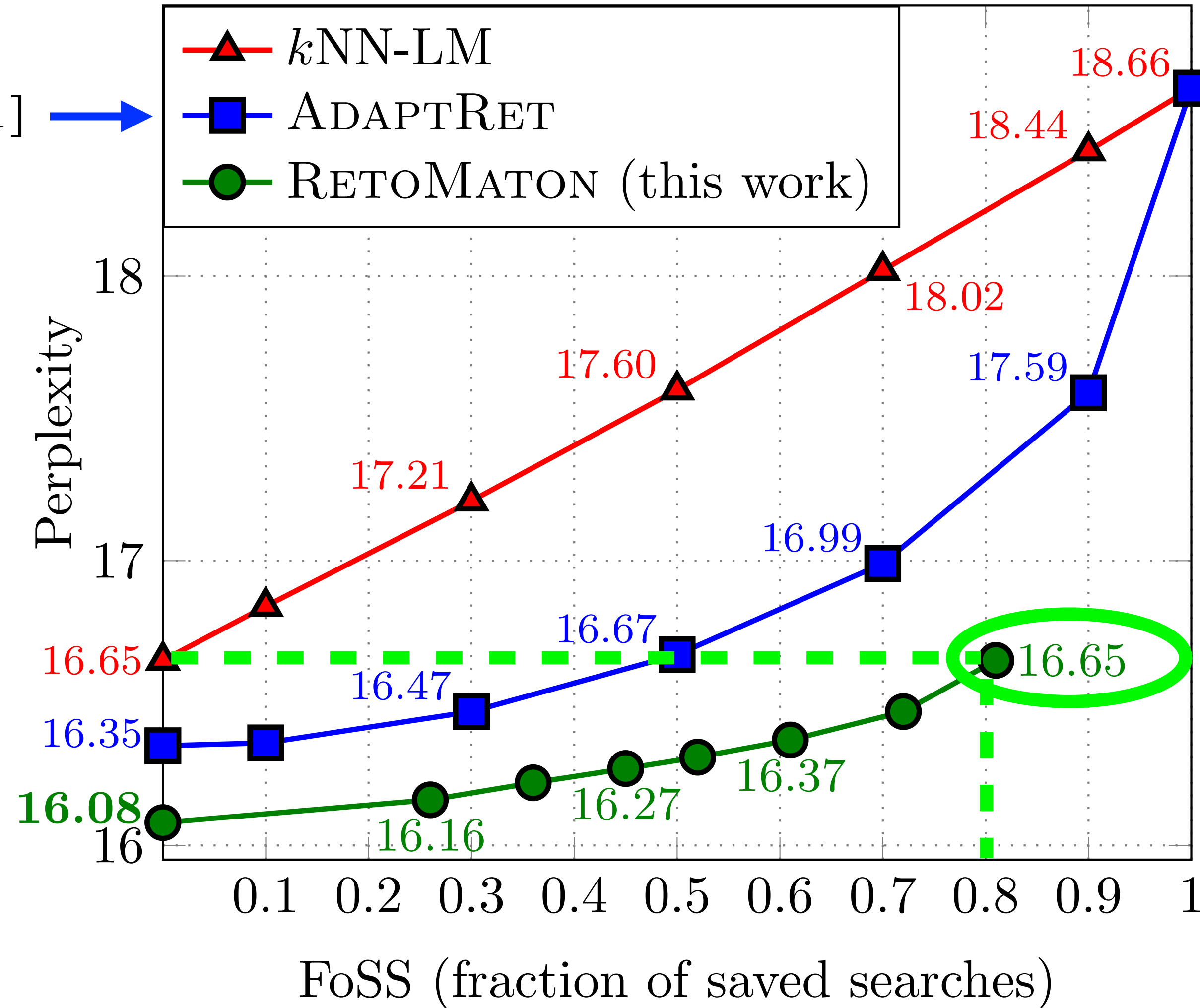
Wikitext-103

[He et al., EMNLP'2021] →



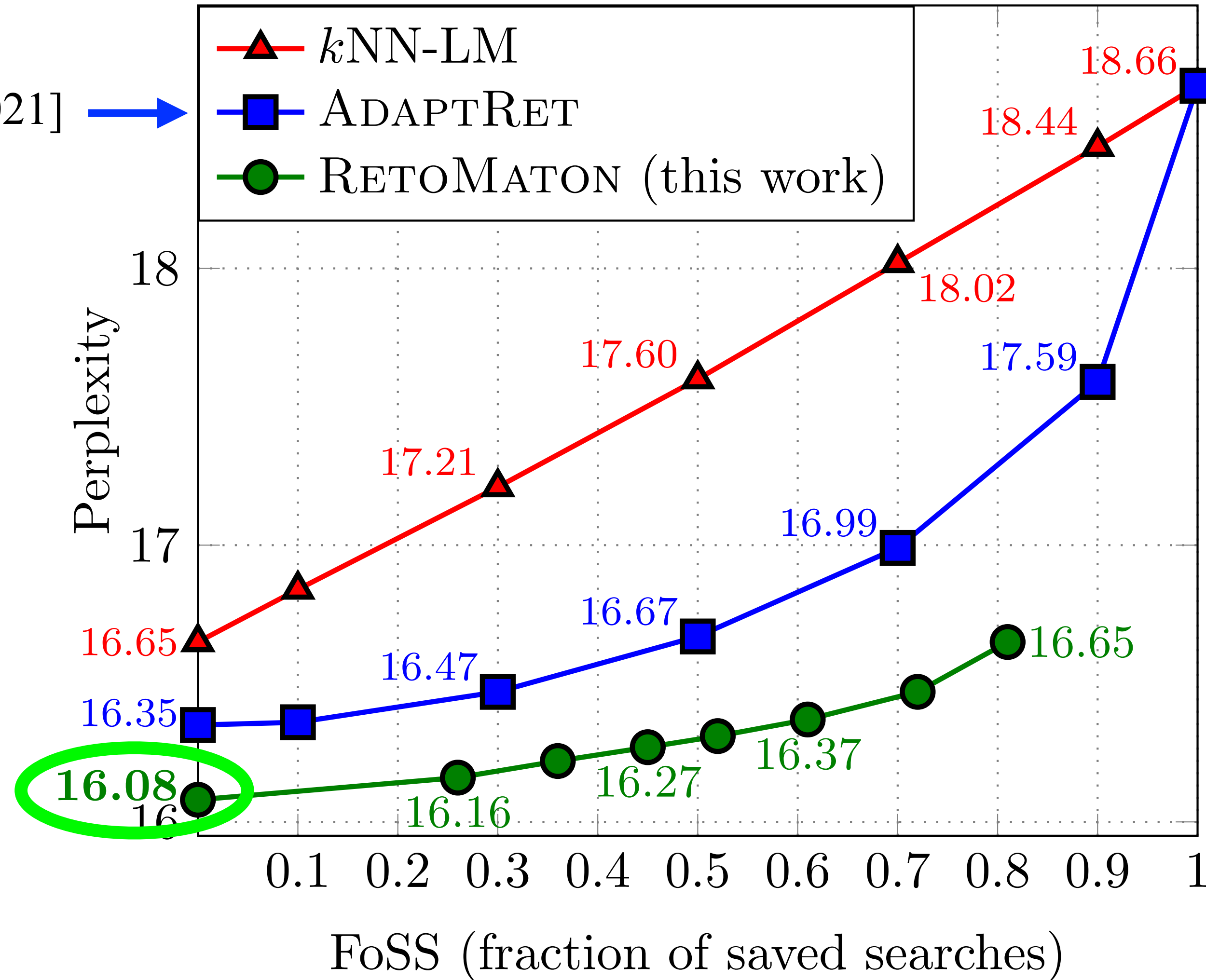
Wikitext-103

[He et al., EMNLP'2021] →



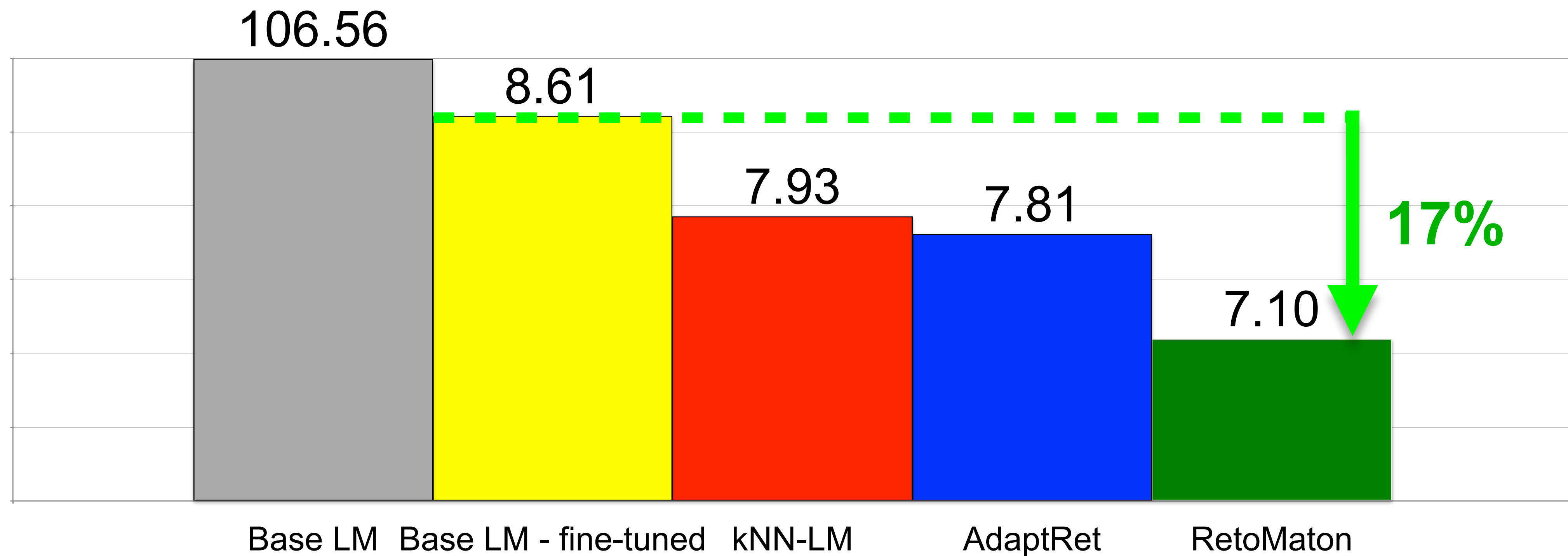
Wikitext-103

[He et al., EMNLP'2021] →



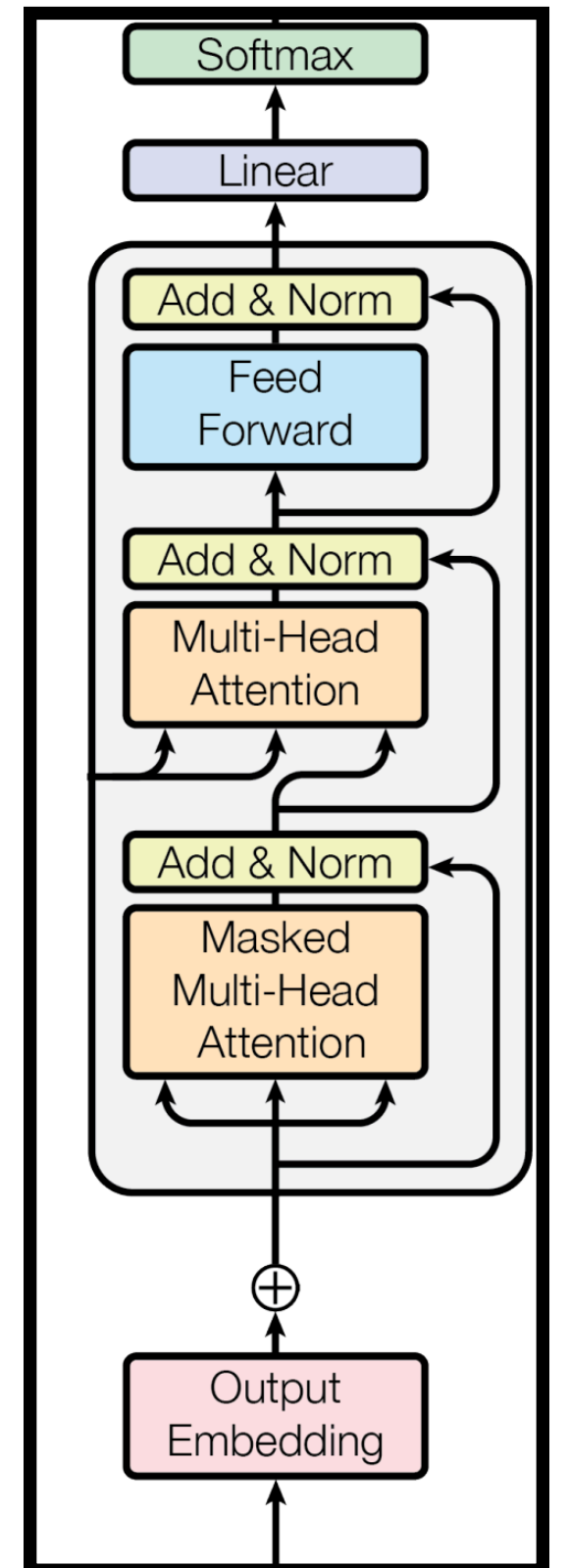
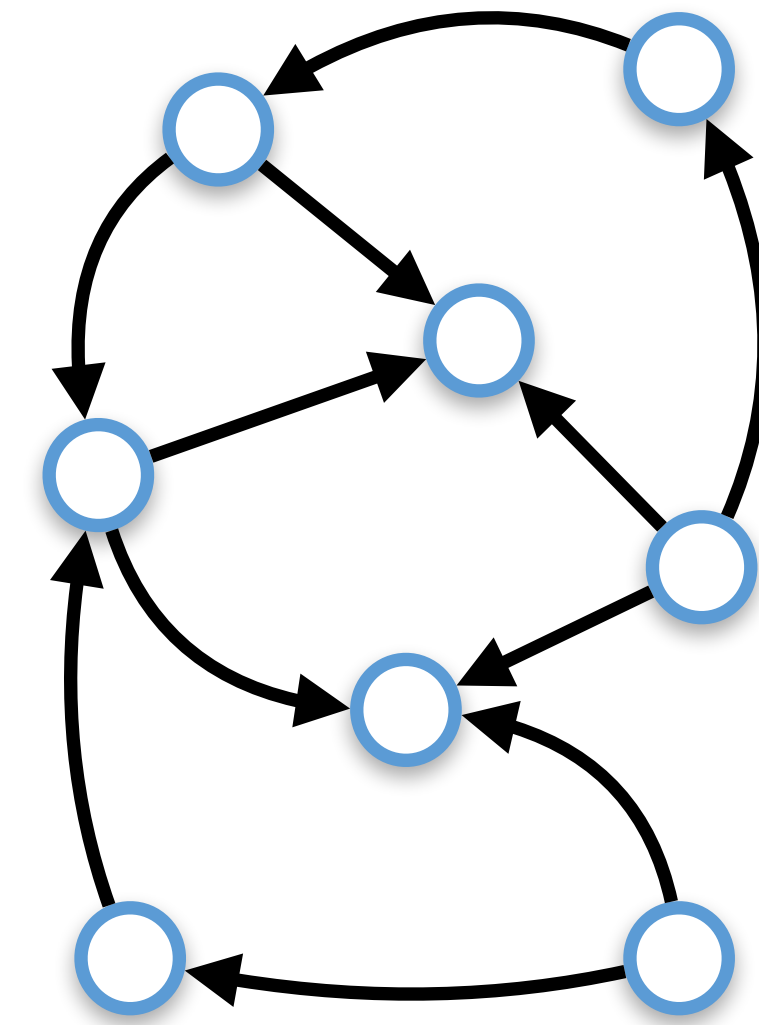
Domain Adaptation

Train on WMT News Crawl; Test+build datastore on Law



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- Synergy between a **symbolic** automaton and a **neural** LM
- Saving **pointers** between training entries
- **Clustering** of entries into automaton states
- **Dynamic** transition scores
- Lower perplexity than the base LM, while saving up to **83%** of the k NN searches compared to k NN-LM
- The creation of the automaton is **unsupervised**
- Constructed from the original training data
- Another domain



Please visit our poster session!

<http://urialon.ml>

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<https://github.com/neulab/retomaton>

<https://github.com/neulab/knn-transformers>